

# Use of Linear Aircraft Intent Response for Tactical Trajectory Based Operations

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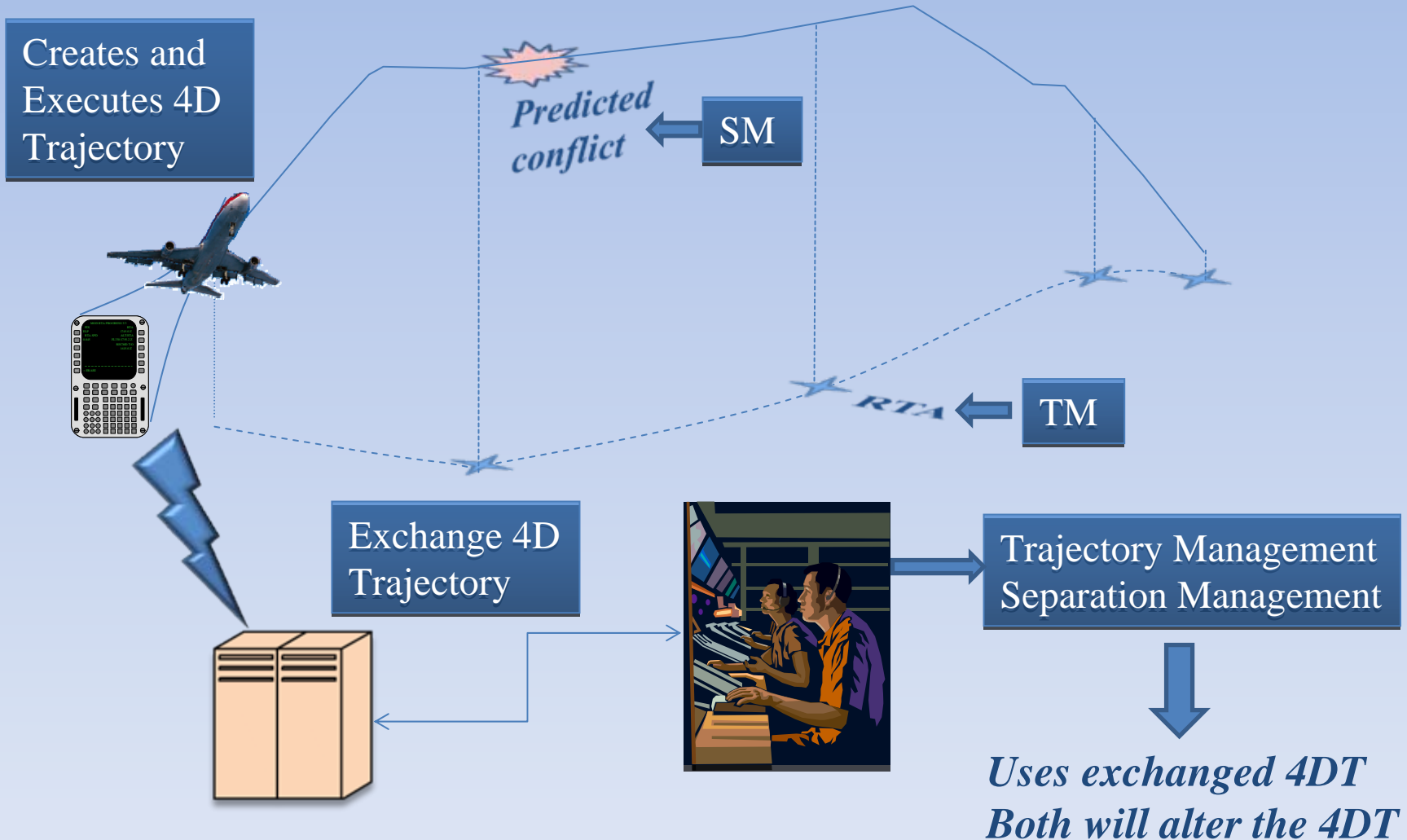
*\*This work was conducted  
under contract for the FAA  
while Dr. Mondoloni was  
employed at CSSI Inc.*

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CA June-July 2009

# Overview

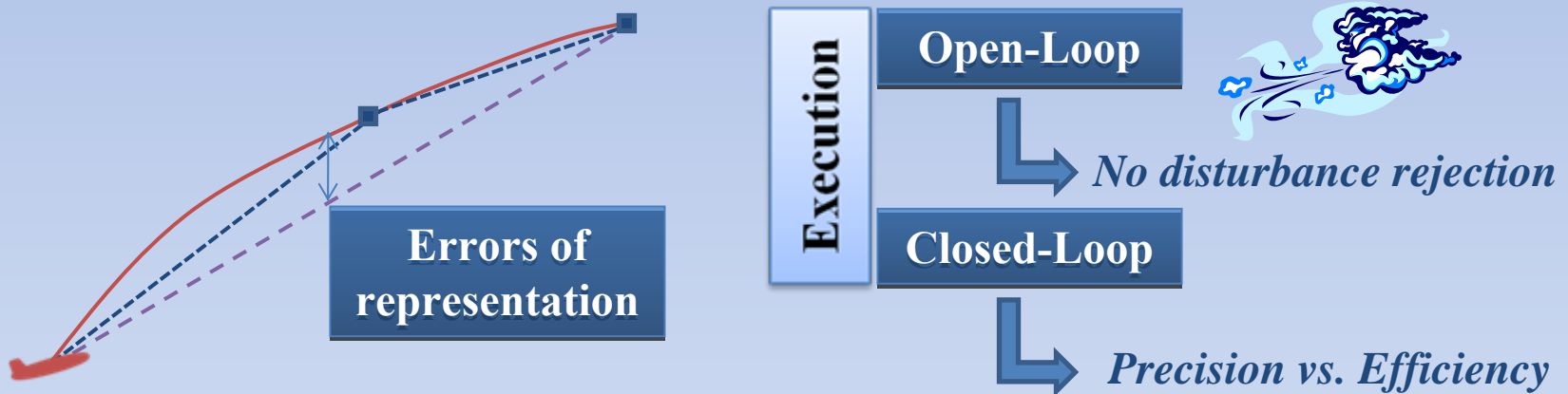
- Motivation
- What is Aircraft Intent Response?
- Evaluation of Approach
  - Metrics
  - Path stretch
  - Altitude
- Summary & Conclusions

# Trajectory & Separation Management



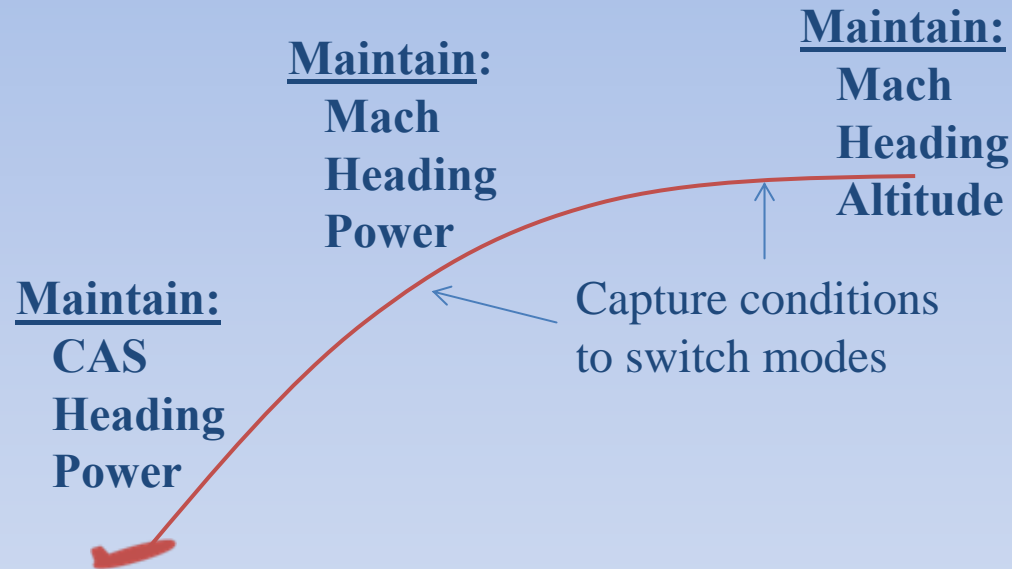
# The exchanged 4DT

- Exchanged 4DT subject to errors, e.g.:



- Exchanging aircraft intent<sup>†</sup> :
  - Can reduce errors of representation
  - Provide means to model excursions

# Aircraft Intent Example



Ground DST uses aircraft intent:

- Constructs continuous aircraft trajectory
- Updates effects of disturbances with surveillance data
- Trajectory used for problem detection

# Modifying the 4DT

- Problem is detected with shared 4DT
- Several DOF available to solve:



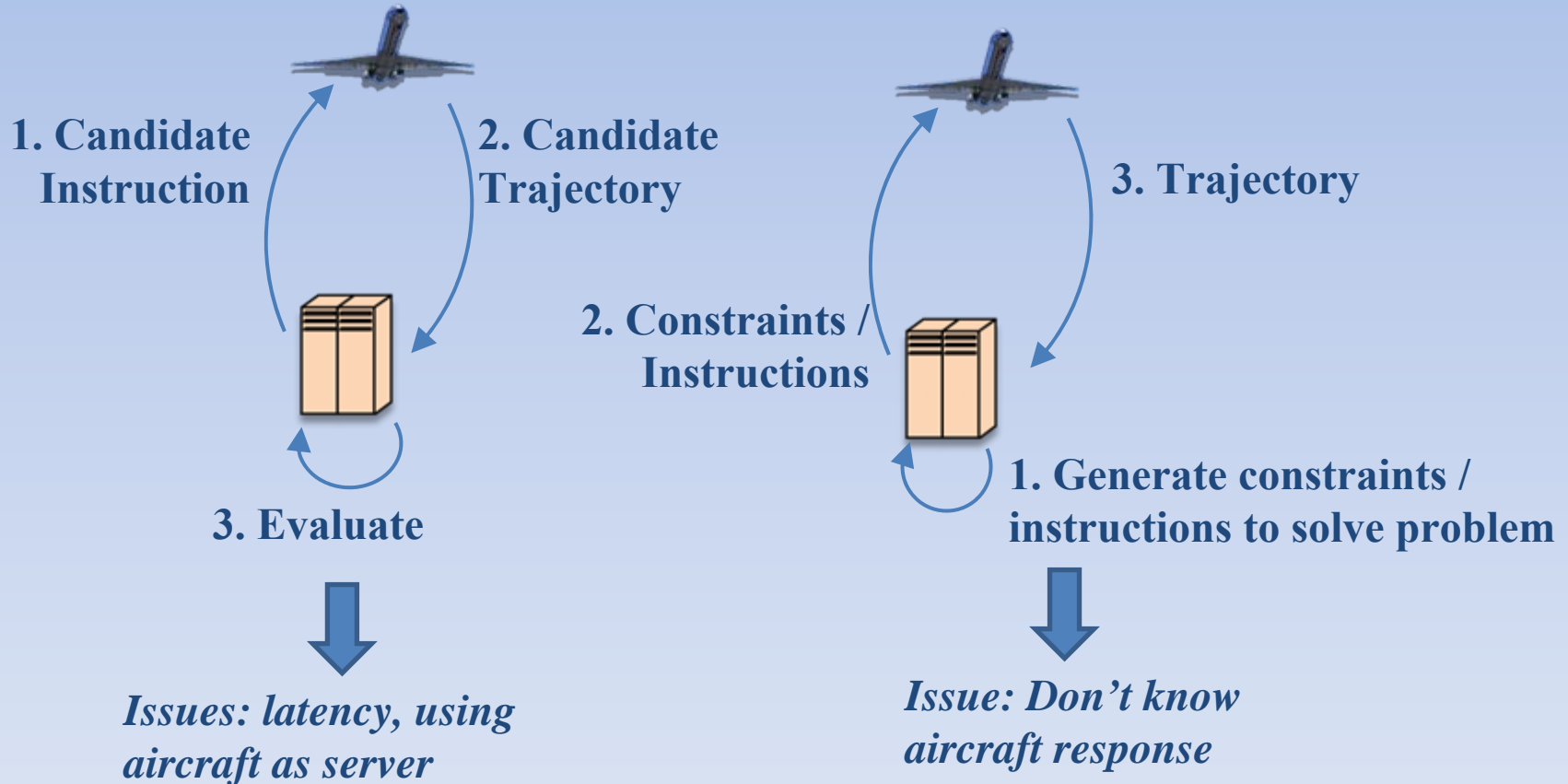
The “what-if?”  
case



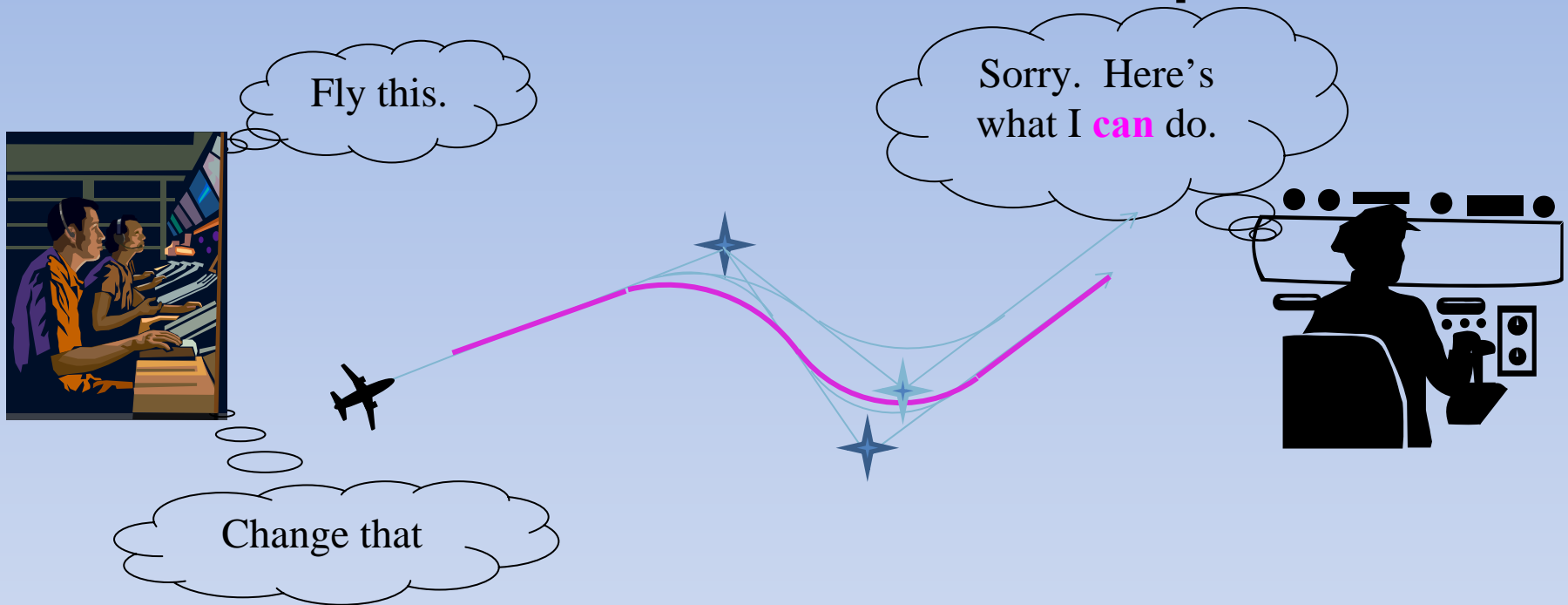
- DST evaluates alternative “instructions”
- Ensure instructions yield a problem-free 4DT
- Predicted 4DT must be feasible & accurate
- Uplink instructions, not a 4DT

# Options for What-if?

## 0. Problem Detected



# Don't know aircraft response

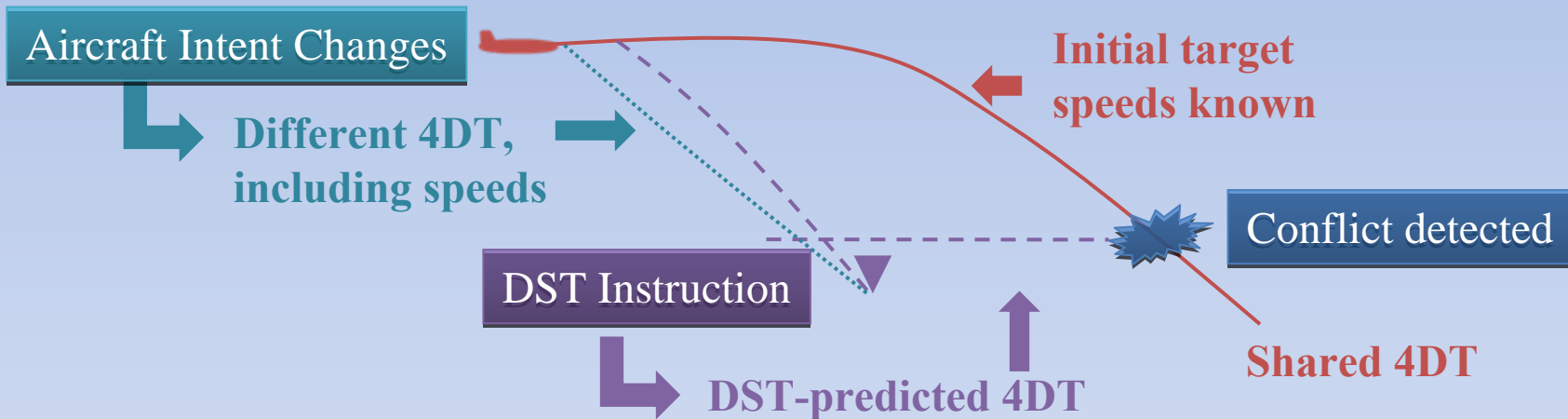


- Tactical decisions – time criticality impacts allowable exchange
- Could use buffers – but leads to inefficiencies and loss of capacity
- What information can we use to do better “what-if-ing”?



# The Problem

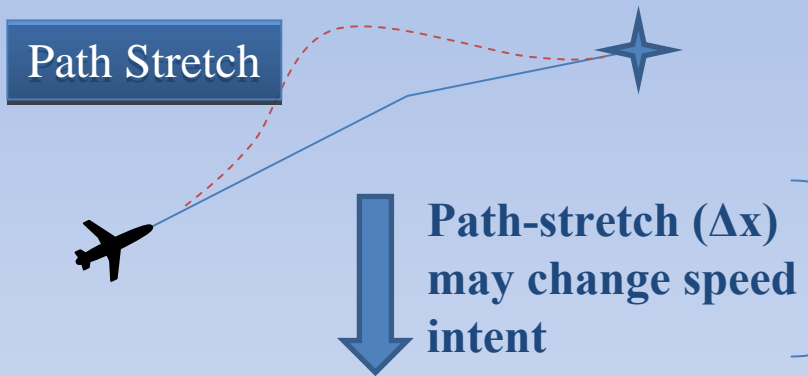
- Instructions can change the aircraft intent\*



- Look at using 1<sup>st</sup> order change in aircraft intent based on instruction to improve accuracy

*\*Aircraft intent in this case does not represent aircraft objective functions, but represents an unambiguous description of how the trajectory is to be executed.*

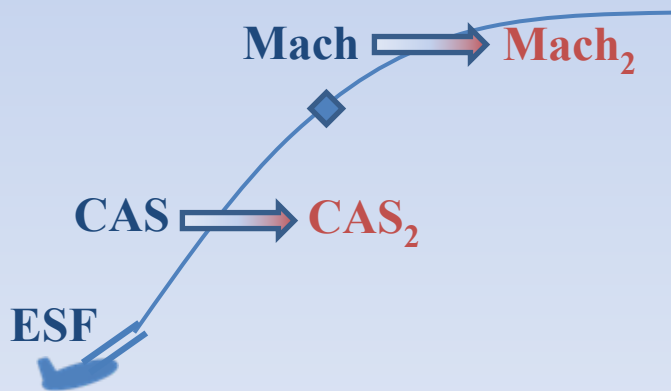
# Linear Aircraft Intent Response



## Why?

- Explicit CTA
- Implicit Time Target
- Open-loop on time

➤ **Solution is under-determined**

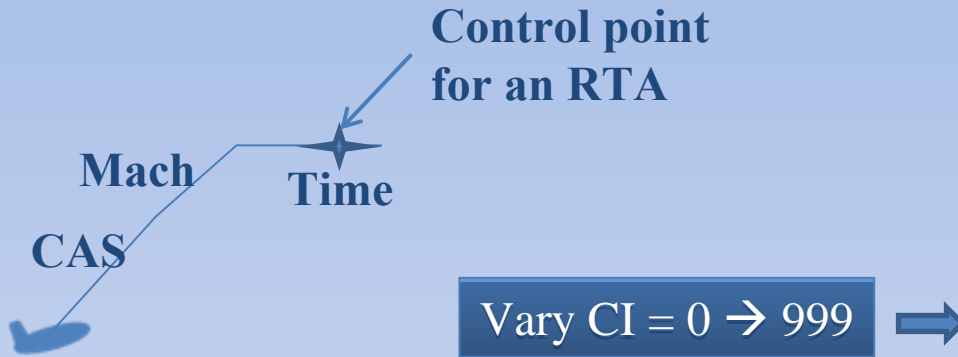


Apply very simple linear formulation:

$$M_2 = M + \frac{\partial(M)}{\partial(\Delta x)} \Delta x$$

$$CAS_2 = CAS + \frac{\partial(CAS)}{\partial(\Delta x)} \Delta x$$

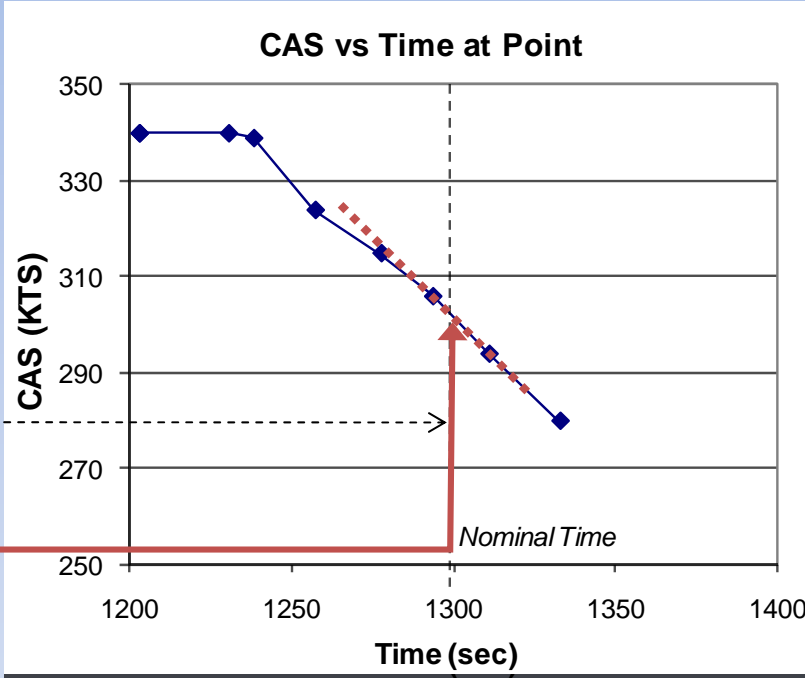
# LAIR – Example path-stretch



Vary CI = 0 → 999

But there is an RTA

Obtain slope

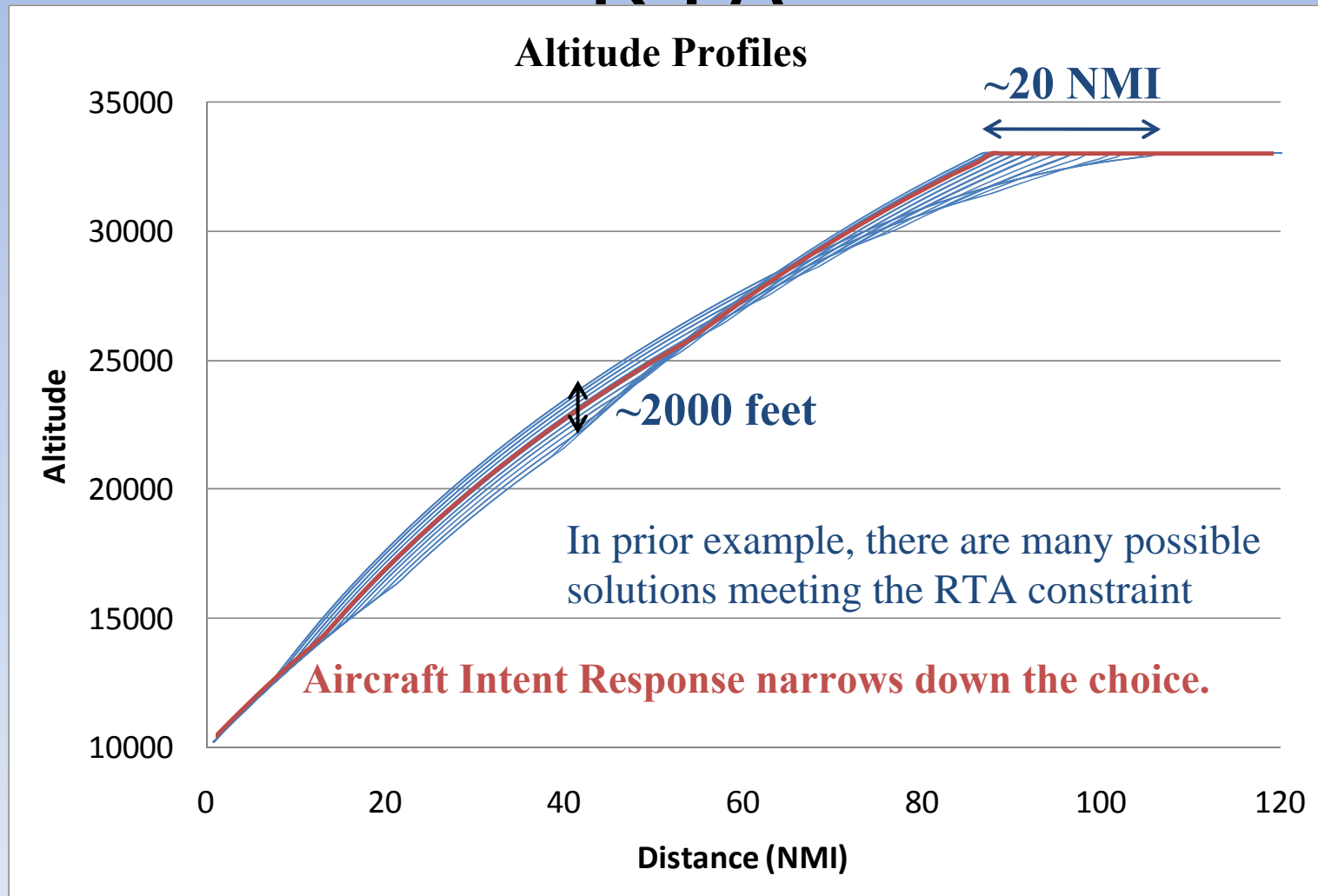


$$\frac{\partial(CAS)}{\partial(\Delta x)} = \frac{1}{V_{avg}} \frac{\partial(CAS)}{\partial(\Delta t)}$$

*Estimated time at the control point as vary CI*

- With sensitivity, ground better estimates effect of path stretch
- Aircraft knows its own meet-time algorithm, provides sensitivity

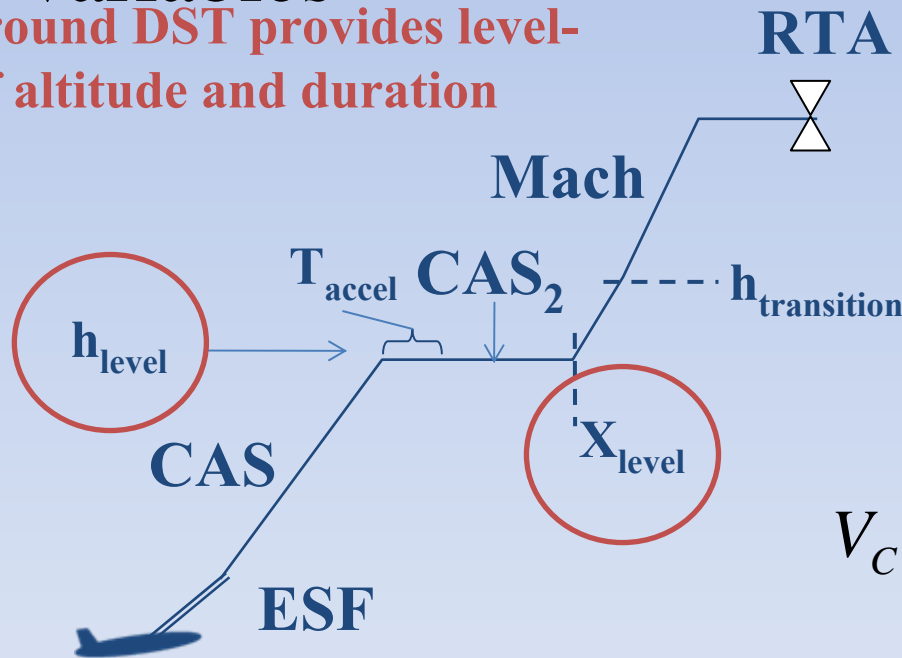
# Alternative Profiles Meeting RTA



# LAIR – Level off example

- Temporary altitude in climb has more variables

Ground DST provides level-off altitude and duration

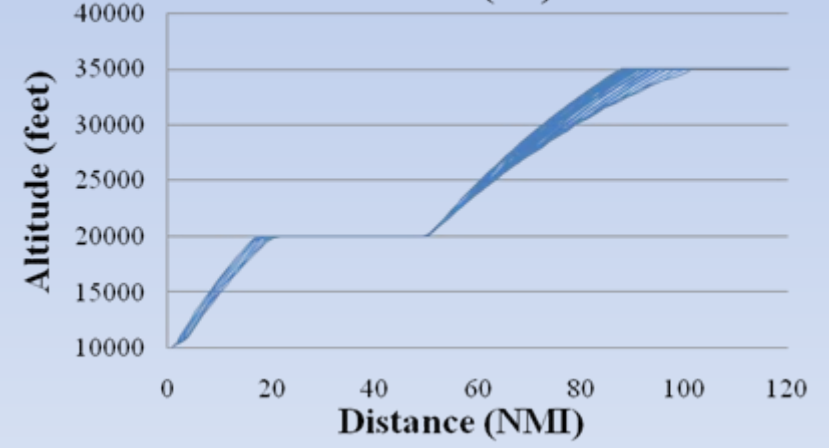
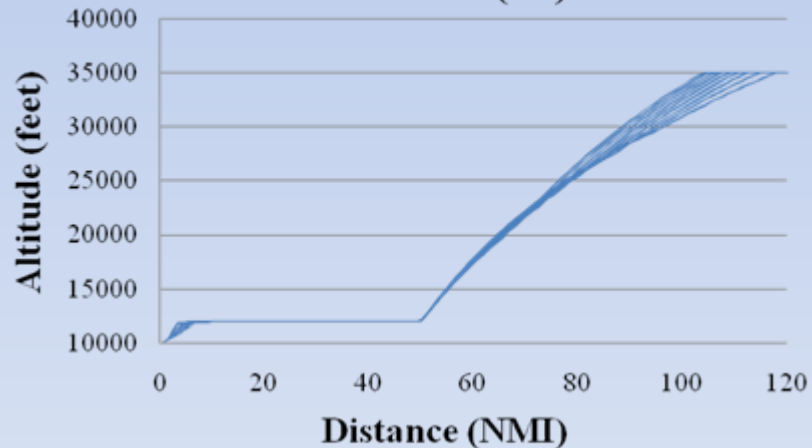
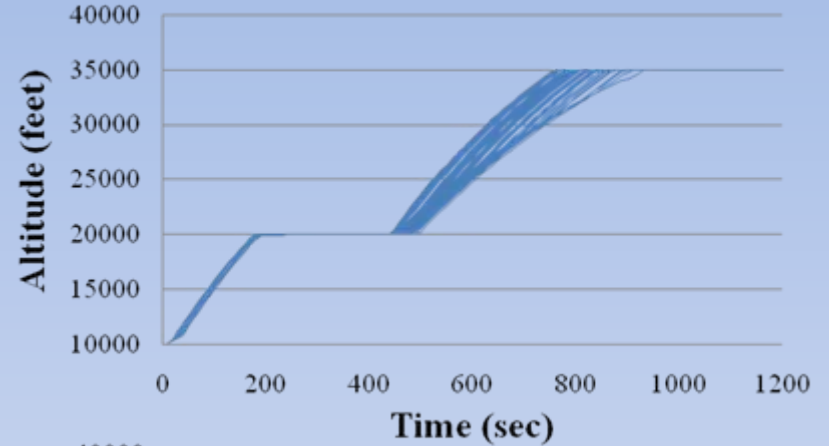
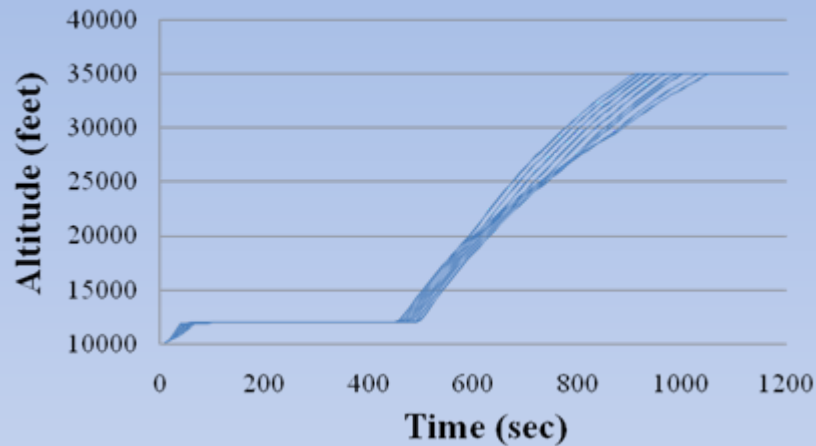


Use sensitivities to estimate new speeds

$$V_c = \begin{bmatrix} 1 & x_{level} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} 1 \\ h_{level} \end{bmatrix}$$

$$V_{CAS_2} = \max \{ V_{min}, \min(V_{max}, V_c) \}$$

# Alternative level-off profiles

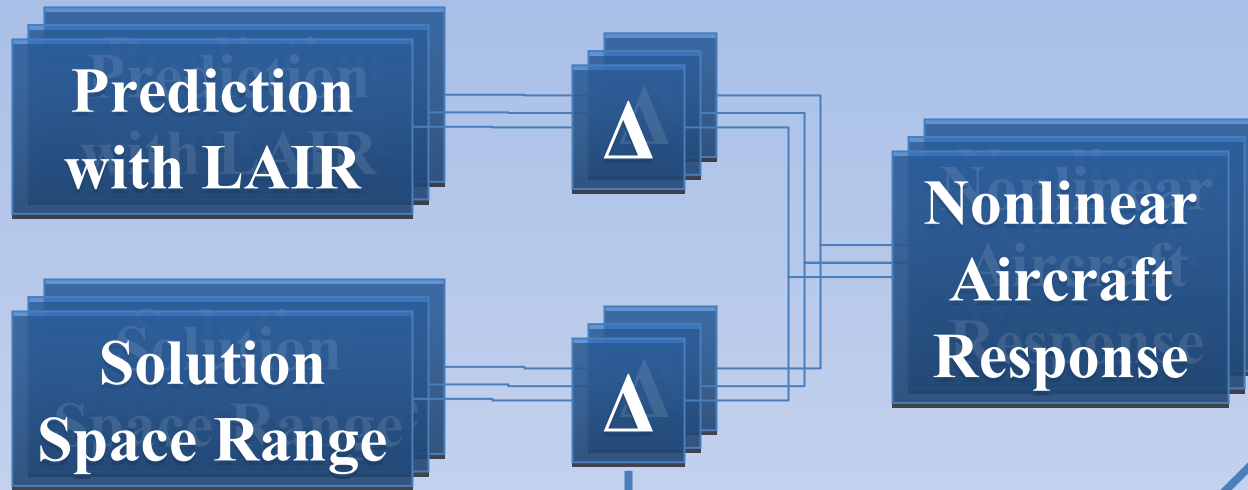


Identical instructions

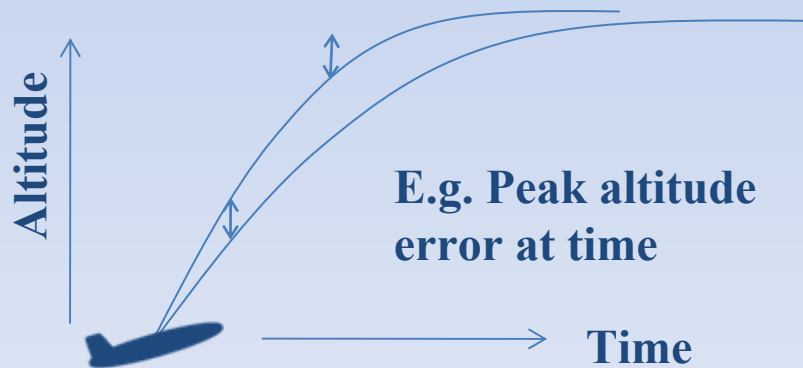
Different aircraft response

4D Trajectory variation

# Obtaining Metrics



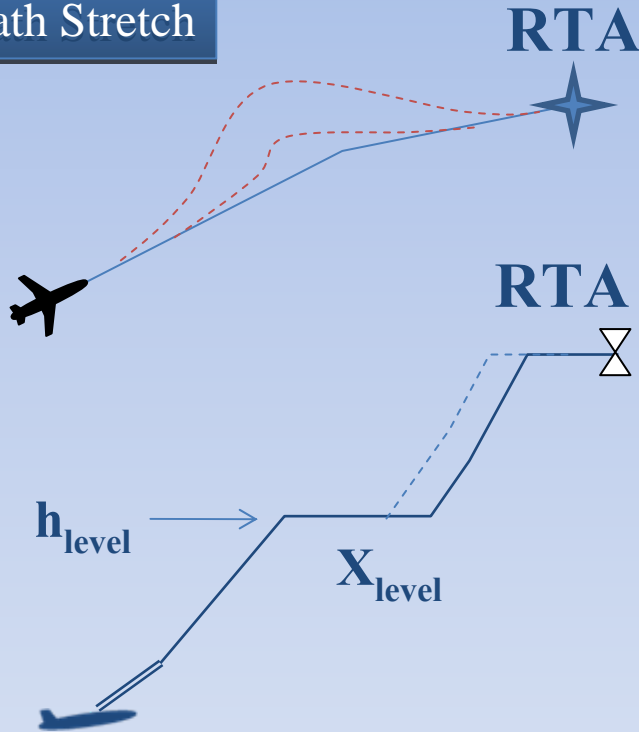
Obtain peak error metrics



Collect RMS on peak errors across multiple cases

# Cases

Path Stretch



**PS-40: Path stretch w/ 40 seconds delay**

**PS-80: Path stretch w/ 80 seconds delay**

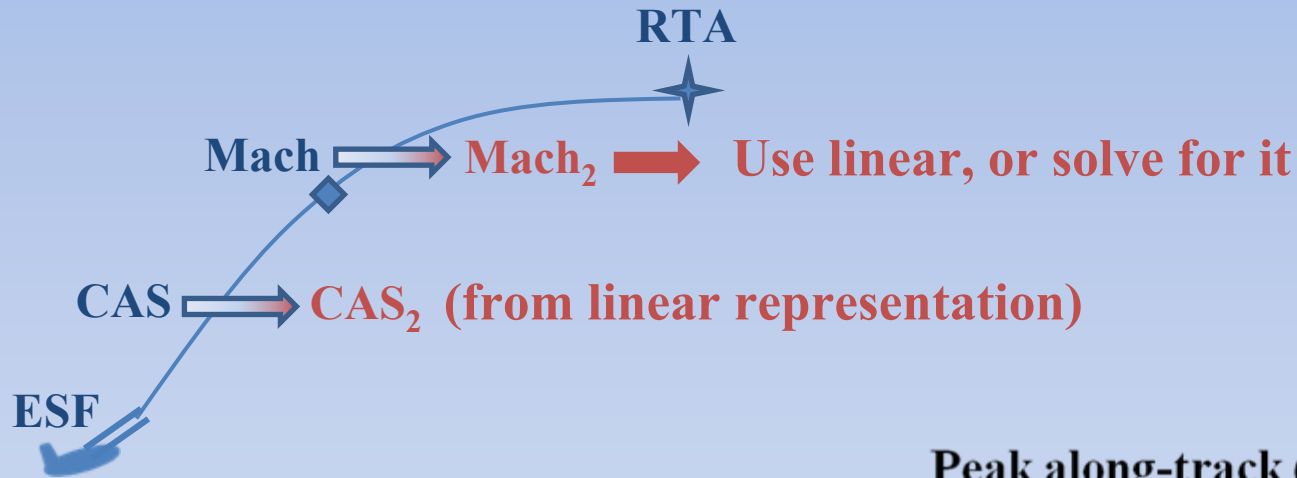
**Alt-50: Altitude hold for 50 NMI**

**Alt-75: Altitude hold for 75 NMI**

*Vary flight parameters: cruise level, weight, level-off altitude*



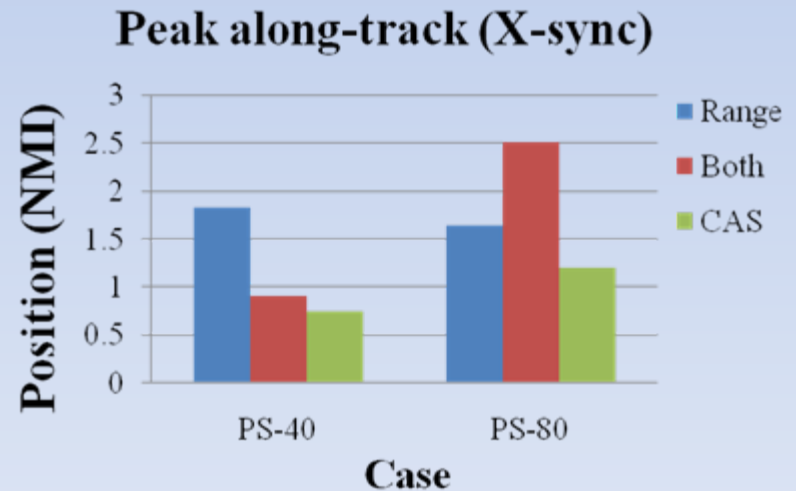
# Appropriate Representation



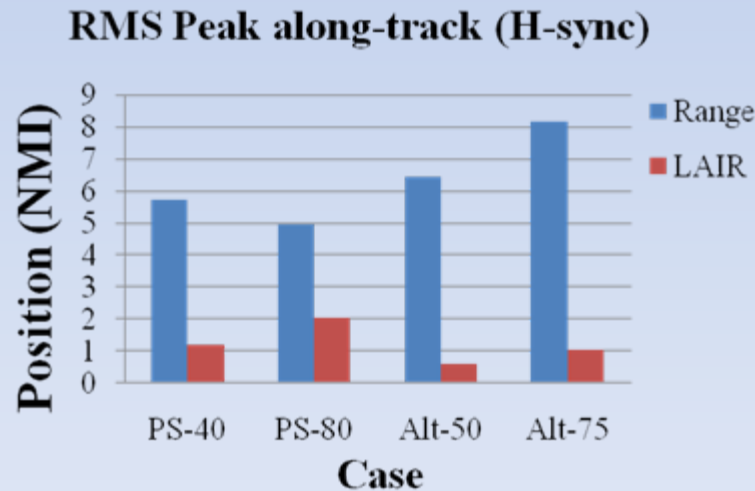
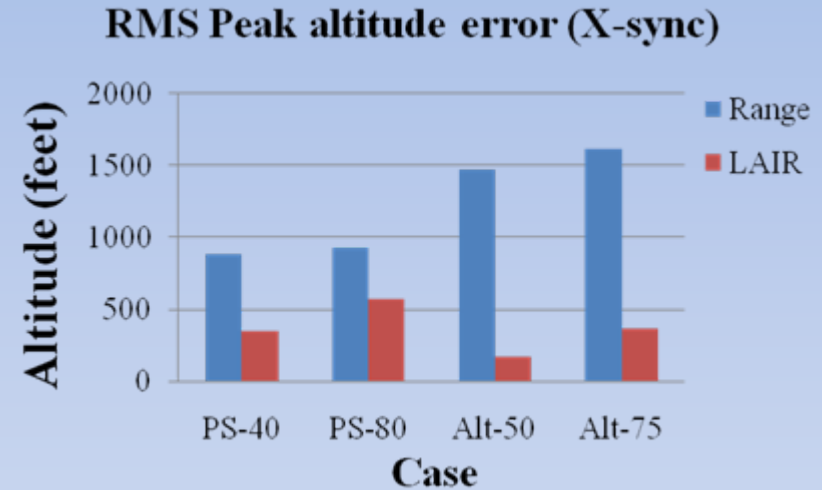
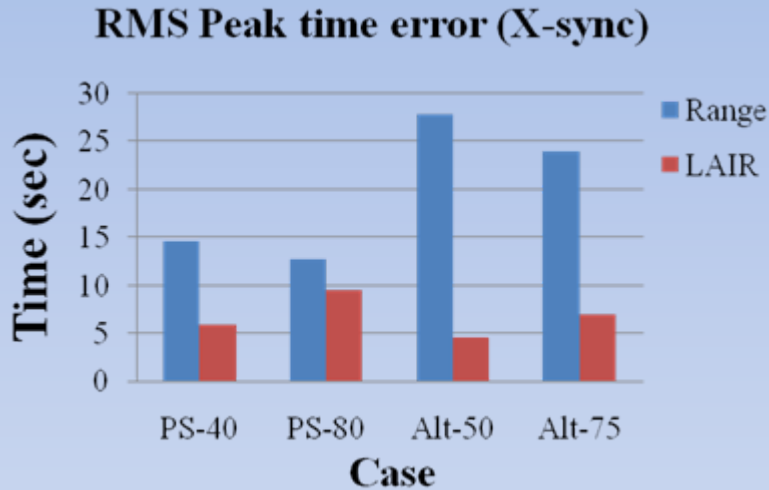
Using both as linear, don't meet the RTA for PS-80!



→ Use enough parameters, but no more



# Results – LAIR reduces errors



*N.B. Errors due to lack of precise intent*

# Summary

- Aircraft intent exchange
  - Reduces errors of representation
  - Provides ability to model excursions
- Ground-based, tactical DSTs need 4DT Prediction
  - Feasible – instructions must be executed
  - Accurate – efficiency & capacity impact via buffers
- Exchange of linear aircraft intent response for “what-if”
  - Significantly improves accuracy due to lack of intent
  - Can provide limits (for feasibility)

# Conclusions

- Linear aircraft intent response
  - Provides one approach for removing the “*but you don’t know what the aircraft’s going to do*” anxiety
  - First order sensitivity provides large intent-error reductions (34-90+% reduction in various metrics)
  - Small additional information exchange required
  - No need to exchange objectives and cost functions
- This effort was exploration
  - Further investigation into general formulations for exchange
  - Compatibility with aircraft intent approach