

# MODELLING AND ESTIMATION OF SEPARATION CRITERIA FOR AIRBORNE TIME-BASED SPACING OPERATION

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- **Aim of this Paper**
- Monte Carlo Simulation
- Simulation Results
- Interaction with ACAS
- Concluding Remarks



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# Aim of this Paper

- To gain insight on how collision risk depends of the minimum separation criterion for the Airborne Time-Based Spacing (TBS) operation;
- In order to achieve so, initial collision risk results obtained through modelling and simulation of Airborne TBS operation are presented.

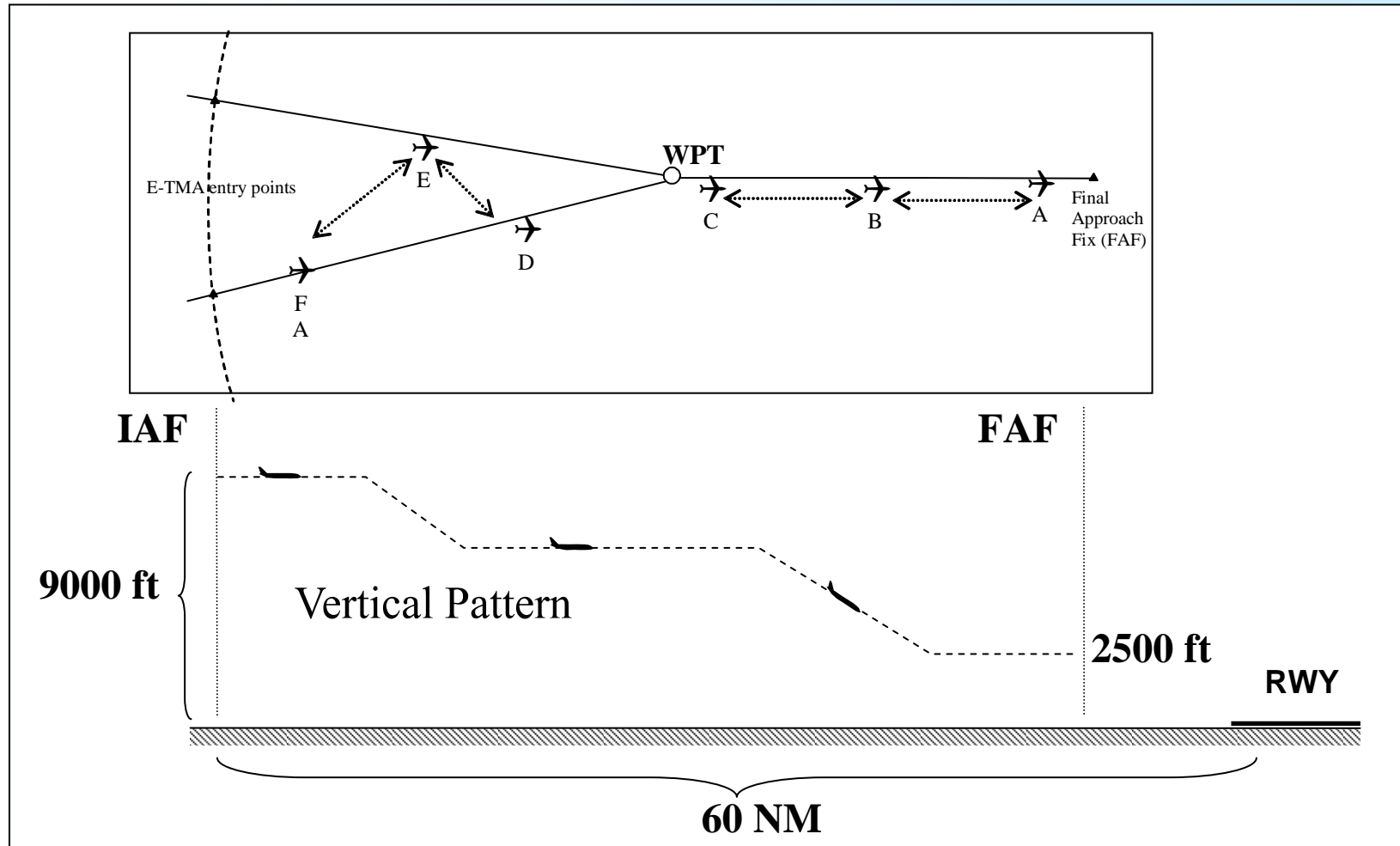


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# Airborne TBS Operation

Focus on E-TMA airspace, until final approach fix



# Airborne TBS Operation

## New kind of ATCo instructions

### Phase 1

-Select target

### Phase 2

-Remain behind

-Merge behind

## Tasks of flight crew

- Be aware of the surrounding traffic;
- Identify the target aircraft on the CDTI;
- Activate Merge/Remain mode
- Monitor spacing (when using spacing director);



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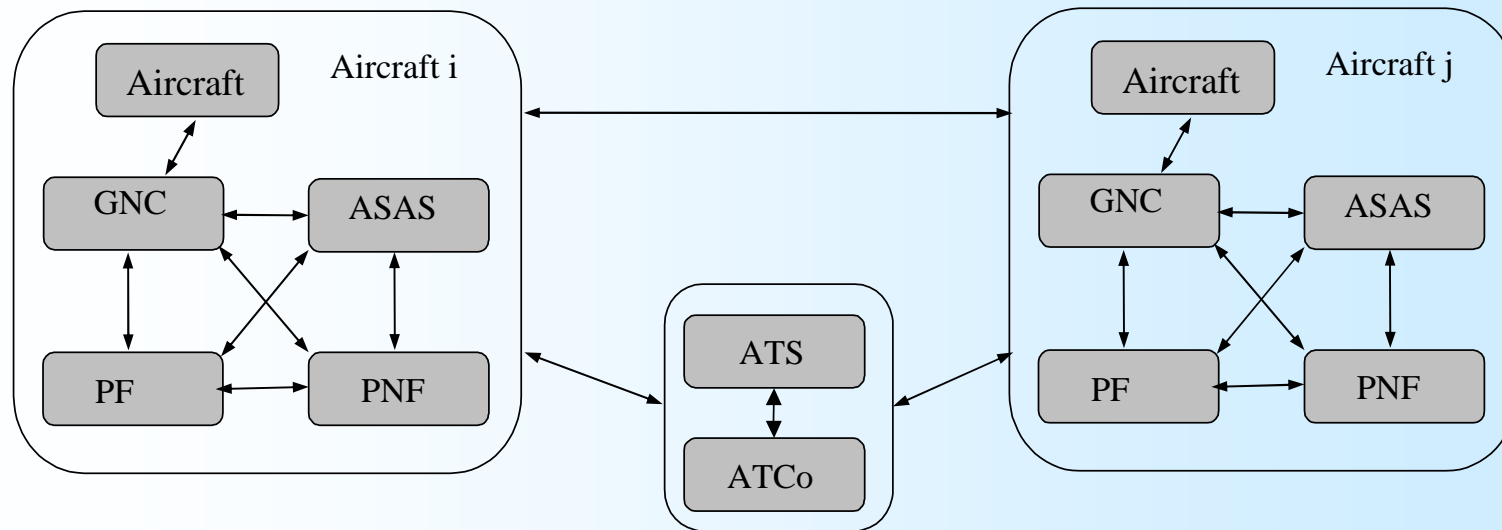


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# Monte Carlo Simulation

## Multi-Agent Joint Cognitive System



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# Monte Carlo Simulation

## Model parameterization, verification and validation

- A Multi Agent model is developed and coded in Java programming language;
- This JAVA code is used to run Monte Carlo simulations for the scenarios considered;
- The Multi Agent model enables systematic implementation, verification and validation, through the following steps:
  - Software code testing in hierarchical levels;
  - Numerical approximation testing, such as choosing an appropriate time step;
  - Parameterization, using several information sources;
  - Initial model validation under some dedicated scenarios;
  - Overall validation against real operational concept (not yet performed)



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# Monte Carlo Simulation

ASAS equipment loop probabilities of failure  
(baseline values used in simulation model)

ASAS computer	0.0001
ADS-B transmitter	0.00005
ADS-Receiver	0.00005



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# Monte Carlo Simulation

## Simulation of Separation Related Events

Event	Horiz. dist. (NM)	Vert. dist. (ft)	Pred. time (min)
Short Term Conflict (STC)	4.5	900	2.5
Minimum Separation Infringement (MSI)	4.5	900	0.0
Near Mid-Air Collision (NMAC)	1.25	500	0.0
Mid-Air Collision (MAC)	0.054	131	0.0



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# Monte Carlo Simulation

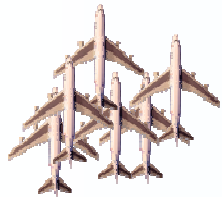
## Straightforward Monte Carlo Simulation



$N$      $m$



$$p = 2/6 = 1/3$$



- How to evaluate the collision probability using a Monte Carlo simulation model?
- The stochastic model is simulated  $N$  times using independent random samples
- When  $m$  collisions are counted, then the estimated collision probability is  $m/N$



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# Monte Carlo Simulation

## Speeding Up Monte Carlo Simulation

- In order to get a statistically valid result for a probability of  **$10 \times 10^{-9}$** , some 100 collision occurrences should be counted; which requires to run the Monte Carlo simulation some  **$10 \times 10^{11}$  times**;
- If one Monte Carlo simulation run takes 0.1 second, then the Monte Carlo simulation takes **317 years**;
- In order to reduce this to **1 day**, a Monte Carlo simulation speed up factor of  **$10 \times 10^5$**  is required;
- We accomplish this using advanced speed up methods from financial mathematics



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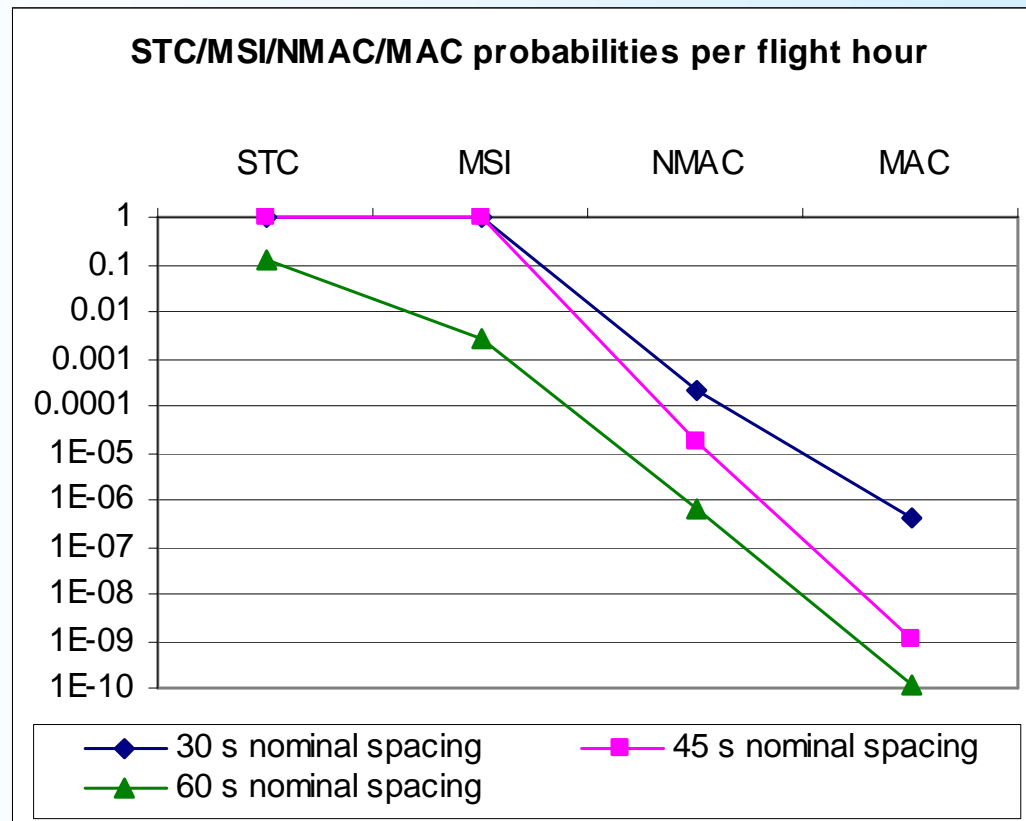


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# Simulation Results

## Probabilities of Separation loss events

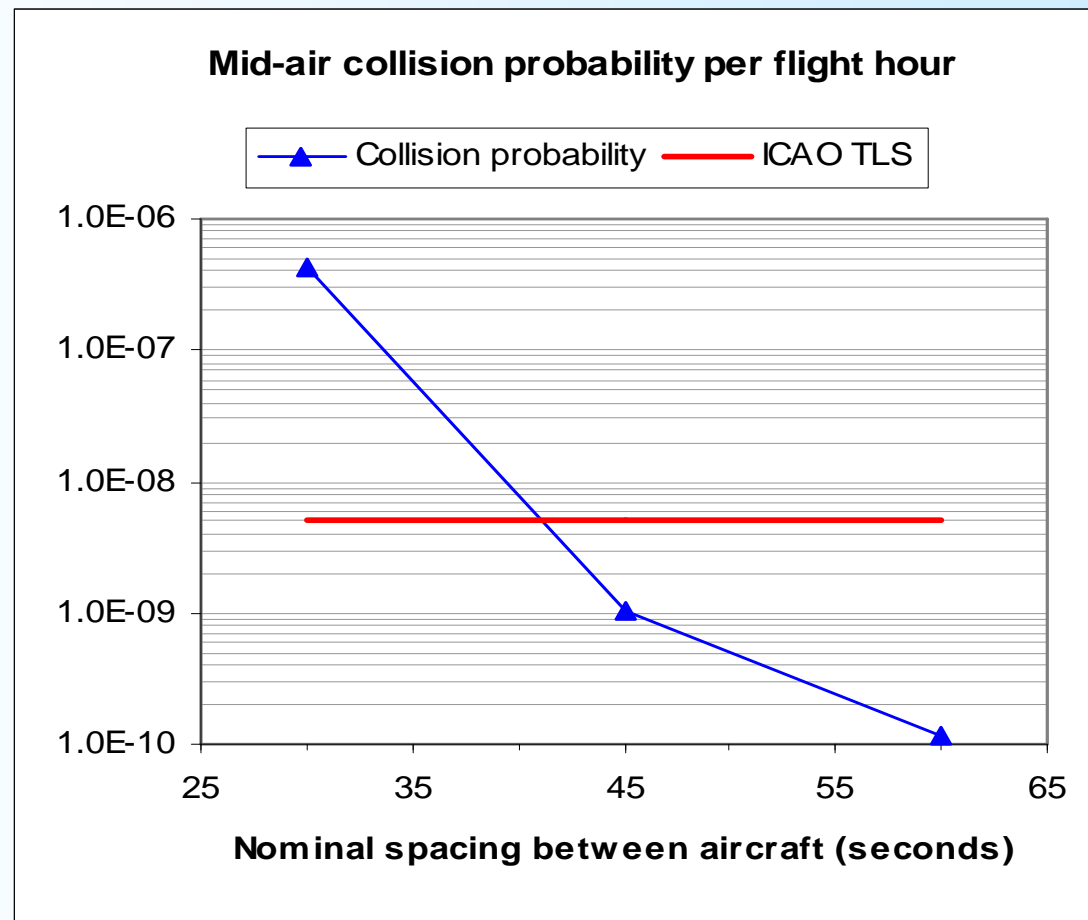


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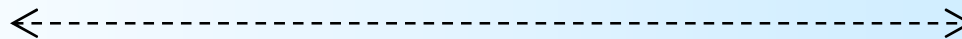


# Simulation Results

## MAC probabilities versus ICAO TLS

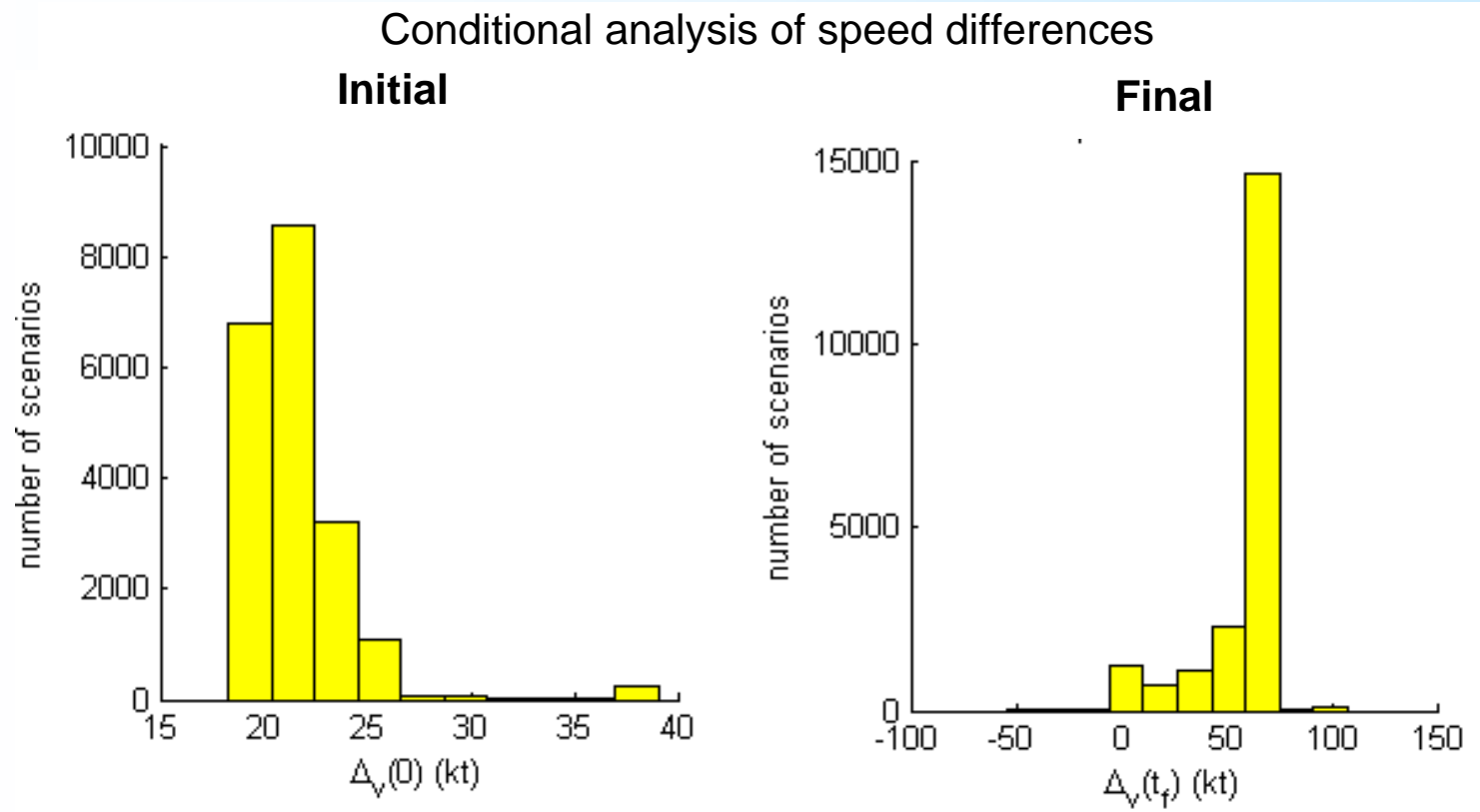


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# Simulation Results

## Speed difference of simulated cases which ended in MAC



Follower aircraft faster than the leader aircraft



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### Causes of higher speed of follower aircraft

- A drifting error existing in the aircraft sensors of airspeed and altitude;
- A peak in the speed caused by starting a descent;
- ASAS spacing failures (including ADS-B).

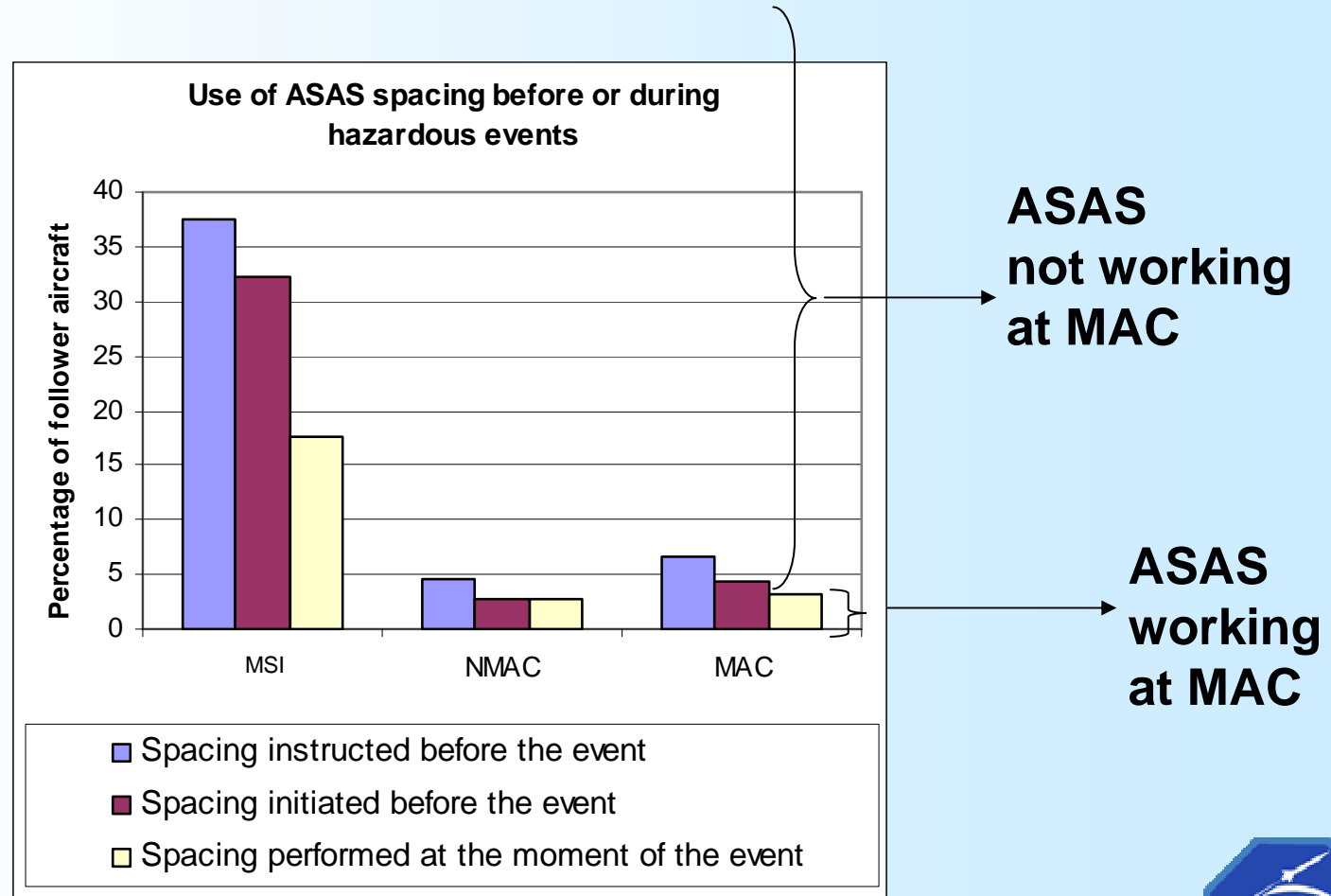


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# Simulation Results

## Working of ASAS for close encounters

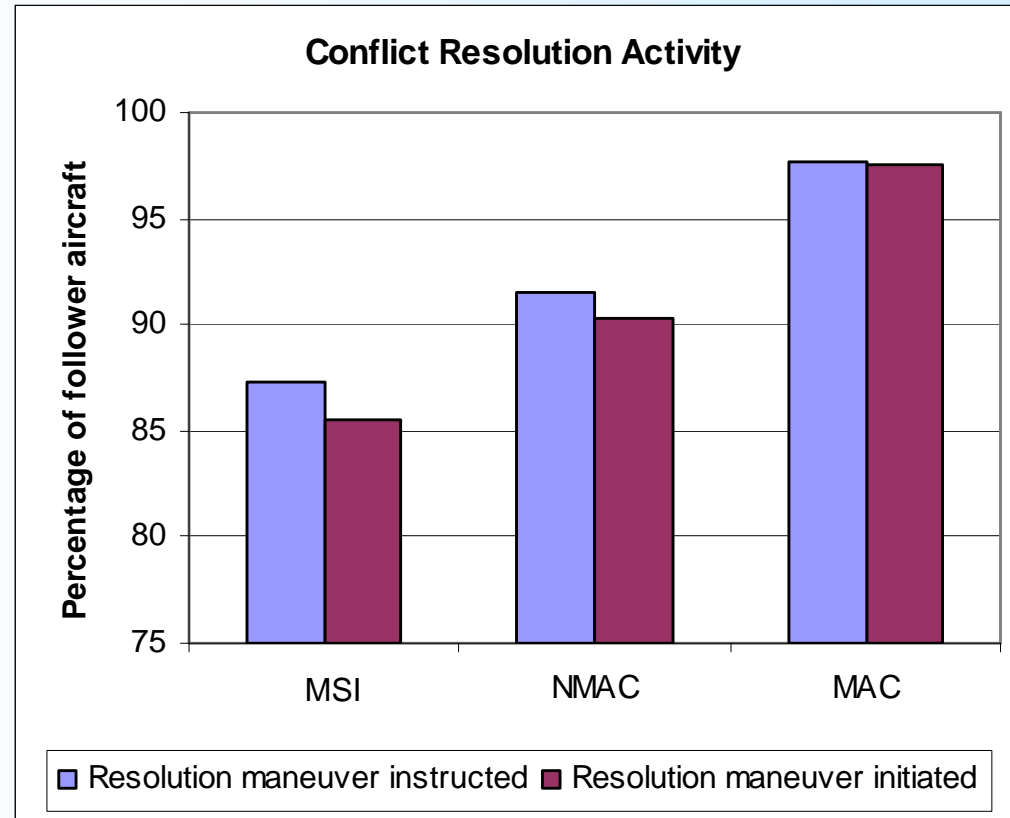


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# Simulation Results

## Conflict detection and resolution



**Conflict resolution initiated, but not effective, typically too late**



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# Interaction with ACAS

- ACAS was not explicitly taken into account in the Monte Carlo simulations;
- However, it is desired to know if ACAS works well with ASAS TBS;
- So ACAS logic has been run “hidden” from the simulated pilots;
- ACAS alerting times have been evaluated in the simulated cases ending in Mid-Air Collision

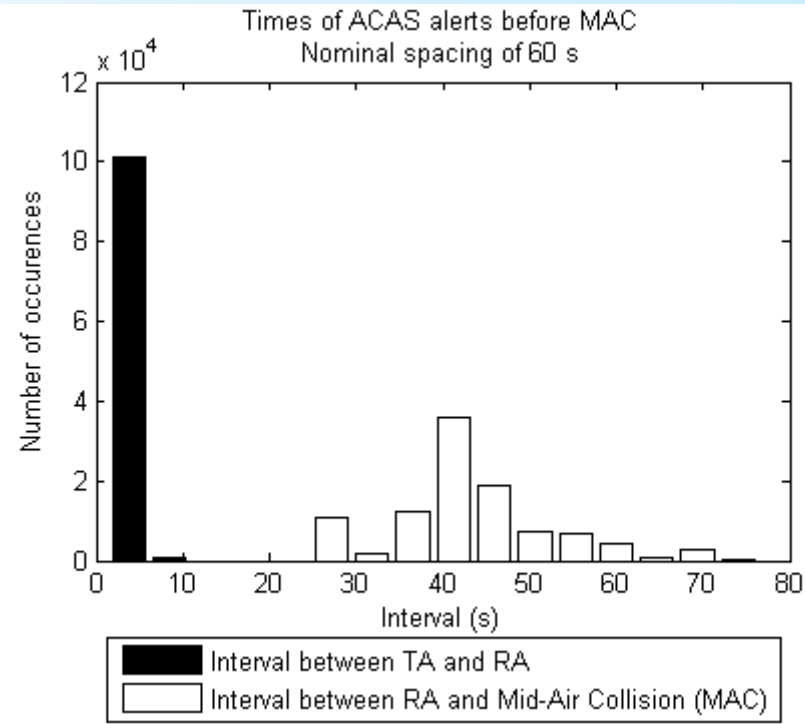
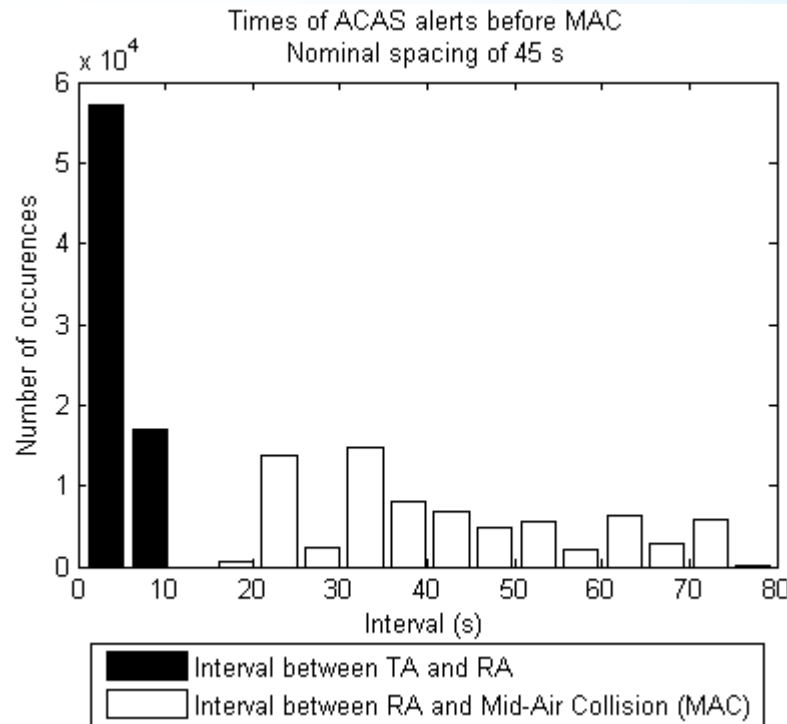


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# Interaction with ACAS

## Intervals between ACAS and Mid-Air Collisions:

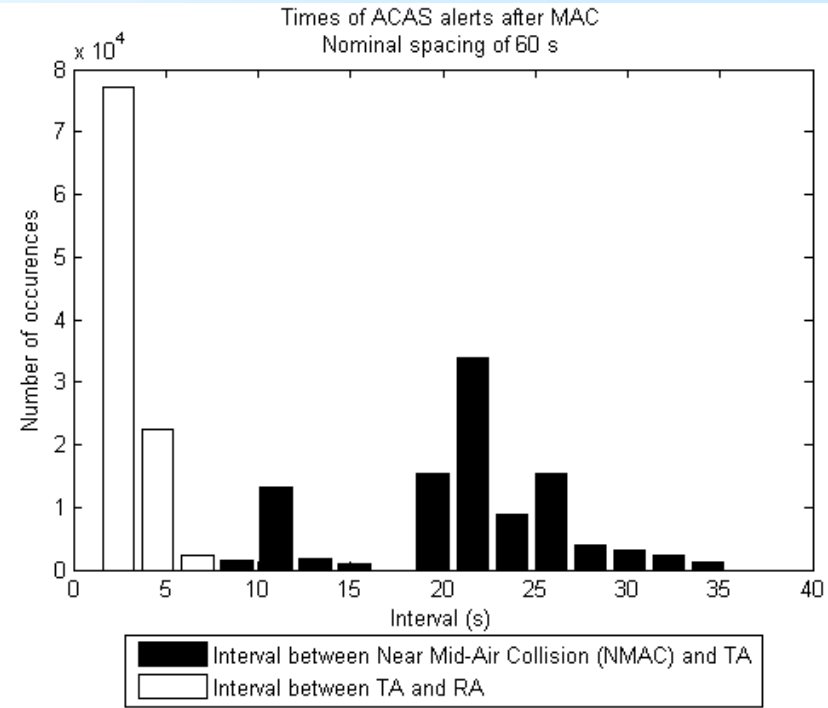
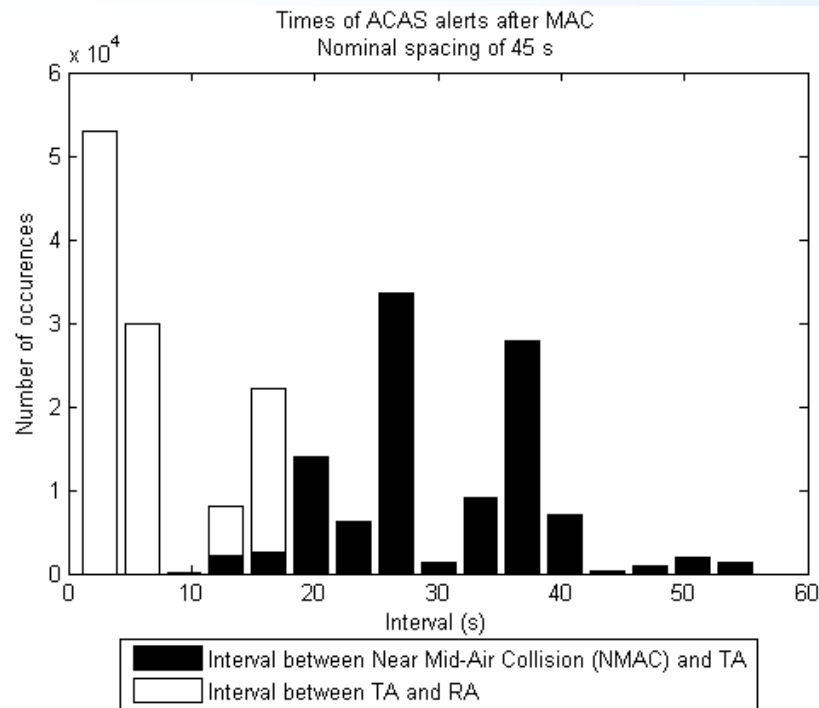


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# Interaction with ACAS

## Intervals between NMAC and ACAS alerts:



- All alerts after NMAC
- This shows that ACAS does not interact too early with ASAS TBS



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# Concluding Remarks

- ASAS TBS is both effective and safe on collision risk at nominal spacing of 60 seconds or more;
- For nominal spacing of 45 seconds, ASAS spacing operation failure is the main contributor for the collision risk, typically due to:
  - ASAS equipment failure;
  - Too small initial separation, from upstream sector;
  - Too large speed difference.



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## Concluding Remarks

- Nominal spacing going significantly below of 60 seconds seems to be an invalid option.
- Follow up reseach:
  - To assess the impact differences between model and reality have on the risk level;
  - Perform Monte Carlo simulations with multiple aircraft trailing;
  - Assess Wake vortex induced risk as fuction of time based nominal spacing value (for various pairs of aircraft).



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# The End



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